

Changes in average and extreme precipitation in two regional climate model experiments

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ABSTRACT

Two regional climate model experiments for northern and central Europe are studied focussing on greenhouse gas-induced changes in heavy precipitation. The average yearly maximum one-day precipitation $P_{\max}$ shows a general increase in the whole model domain in both experiments, although the mean precipitation P_{mean} decreases in the southern part of the area, especially in one of the experiments. The average yearly maximum six-hour precipitation increases even more than the one-day $P_{\max}$, suggesting a decrease in the timescale of heavy precipitation. The contrast between the P_{mean} and $P_{\max}$ changes in the southern part of the domain and the lack of such a contrast further north are affected by changes in wet-day frequency that stem, at least in part, from changes in atmospheric circulation. However, the yearly extremes of precipitation exhibit a larger percentage increase than the average wet-day precipitation. The signal-to-noise aspects of the model results are also studied in some detail. The 44 km grid-box-scale changes in $P_{\max}$ are very heavily affected by inter-annual variability, with an estimated standard error of about 20% for the 10-year mean changes. However, the noise in $P_{\max}$ decreases sharply toward larger horizontal scales, and large-area mean changes in $P_{\max}$ can be estimated with similar accuracy to those in P_{mean} . Although a horizontal averaging of model results smooths out the small-scale details in the true climate change signal as well, this disadvantage is, in the case of $P_{\max}$ changes, much smaller than the advantage of reduced noise.

1. Introduction

Potential increases in heavy precipitation allowed by a larger moisture content in a warmer atmosphere are an important (e.g. considering the risk of flooding) and relatively widely studied aspect of greenhouse gas-induced climate changes. There is some evidence of such increases in the observational record for the last 50–100 years, although the increase has not been globally uniform, due probably to the fact that many regional trends are still dominated by the natural variability of climate (Easterling et al., 2000). Model experiments that simulate the response of climate to larger increases in greenhouse gases, such as a doubling of CO_2 ,

generally point toward a continued upward trend in precipitation extremes in the future.

A general greenhouse-gas induced increase in heavy precipitation is a very prevalent model result (e.g. Noda and Tokioka, 1989; Gordon et al., 1992; Whetton et al., 1993; Gregory and Mitchell, 1995; Hennessy et al., 1997; Jones et al., 1997; Zwiers and Kharin, 1998; Meehl et al., 2000). Despite some variation amongst different studies (Parey (1994) found no systematic change in heavy precipitation statistics in the LMD model), this increase may in fact be a more “certain” and globally uniform consequence of an enhanced greenhouse effect than an increasing mean precipitation. Support for this idea comes from a range of studies with several different approaches to characterise the precipitation statistics. For example, in their CSIRO4 general circulation

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model (GCM), Gordon et al. (1992) found a more widespread increase in average rain intensity (averaged over the days with at least 0.2 mm of precipitation) than in the mean precipitation. Using the UKHI and CSIRO9 GCMs, Hennessy et al. (1997) reported a general decrease in the total number of wet days in low and mid-latitudes and an increase in high latitudes, but an increasing number of days with heavy precipitation in almost all latitude zones. In the study by Zwiers and Kharin (1998) of the response of the CCC GCM2 to a doubling of CO_2 , the 20-year return value of daily precipitation was found to increase almost everywhere, in contrast with the mean precipitation which also showed wide areas of decrease. The globally averaged 20-year return value increased by 11% but the global mean precipitation by only 4%. Nevertheless, as in the case with the mean precipitation, the changes in regional heavy precipitation statistics can not be described by a single globally averaged number.

This paper contributes to the research on greenhouse gas-induced changes in heavy precipitation by analysing two 44 km resolution experiments made with the Rossby Centre regional atmospheric climate model (RCA) for northern and central Europe. The two experiments were driven by boundary forcing data from two GCMs, HadCM2 (Johns et al., 1997; Mitchell and Johns, 1997) and ECHAM4/OPYC3 (Roeckner et al., 1996, 1999; Oberhuber, 1993). Our model area has received little detailed attention in earlier studies on the subject, although some results were presented by Gregory and Mitchell (1995) mainly for central Europe and by Jones et al. (1997) in terms of European mean precipitation class frequencies. Furthermore, most studies on greenhouse gas-induced changes in heavy precipitation have thus far been based on GCM rather than regional climate model (RCM) experiments (but see Jones et al. (1997) for an exception). At the very least, the higher resolution of RCMs has the advantage that it allows the magnitude of intense precipitation to be captured more realistically in the control simulations (Christensen et al., 1998).

The main parameter used in this study is the average yearly maximum one-day precipitation $P_{\max}$, a compromise between the need for information on the real, practically important extremes and the need for meaningful statistics from short experiments. Some results are also given for the

average yearly maximum six-hour precipitation $P_{\max 6}$. Unlike some other useful statistics related to heavy precipitation, such as the frequency of precipitation events exceeding a given threshold, the changes in $P_{\max}$ and $P_{\max 6}$ are directly comparable with those of the mean precipitation P_{mean} . For impact researchers, who require estimates of precipitation extremes in a future climate, it is often tempting to assume that the extremes will change with the same relative percentage amount as the mean precipitation, either because a direct evaluation of the extremes from daily model data is considered a difficult task or because such daily data are unavailable. We will study here the similarity between the P_{mean} and $P_{\max}$ changes in the RCA experiments and try to find some explanations for the differences.

Some specific attention is paid to the signal-to-noise issue. The experiments studied here are only 10 years long, which renders their results potentially sensitive to internal variability, particularly concerning the changes in extremes. One symptom of this is the very noisy geographical pattern of the simulated $P_{\max}$ changes, which gives little indication of a reproducible climate change signal. It is shown that the impact of internal variability can be reduced substantially by smoothing the results horizontally. While such smoothing also removes small-scale details in the true climate change signal, this disadvantage does not outweigh the reduced noise. It is also found that a majority of the differences in $P_{\max}$ and P_{mean} change between the two experiments are likely to arise from internal variability, rather than from differences between the two GCMs providing the boundary data for these regional experiments.

Section 2 below describes the RCM used and the two climate change experiments made with different GCM boundary data. $P_{\max}$ and P_{mean} in the control runs are compared with observational estimates in Section 3. The simulated greenhouse gas-induced changes in P_{mean} , $P_{\max}$ and $P_{\max 6}$, and issues related to their physical interpretation, are discussed in Section 4, while the signal-to-noise issue is studied in Section 5. The main findings are summarised in Section 6.

2. The experiments

The two experiments were made with the Rossby Centre regional atmospheric climate

model (RCA) for northern and central Europe, using boundary forcing data from two atmosphere–ocean GCMs, HadCM2 (Johns et al., 1997; Mitchell and Johns, 1997) and ECHAM4/OPYC3 (Roeckner et al., 1996; 1999; Oberhuber, 1993). RCA was run in a rotated latitude–longitude grid at 44 km horizontal resolution and with 19 hybrid levels between the surface and 10 hPa. It was forced by the driving GCMs from its lateral boundaries (eight-point relaxation zones were used) and from below, by sea surface temperatures (SSTs) and deep soil temperatures.

RCA was developed from the version 2.5 of the limited area weather forecast model HIRLAM (Källén, 1996; Eerola et al., 1997), which is used in several European countries. Changes from HIRLAM include several updates to the soil and snow scheme and the inclusion of explicit modules for inland lakes (Ljungemyr et al., 1996; Omstedt, 1999) and the Baltic Sea (Omstedt and Nyberg, 1996). These changes are described in some detail by Rummukainen et al. (2001). For the experiments discussed here, the original HIRLAM radiation scheme was also modified (Räisänen et al., 2000). Unlike the original scheme, the new version allows for increasing CO₂ in climate change simulations. This has nearly eliminated the tendency of RCA to simulate smaller warming in climate change experiments than the driving GCMs, which was present in the earlier 88 km experiments discussed by Räisänen et al. (2001).

The original HIRLAM cloud and precipitation parameterisations are retained. Cloud water is a prognostic variable. It is produced as a result of either stratiform condensation induced by explicitly resolved ascent, or of deep convection parameterised with a Kuo-type scheme (Kuo, 1965; 1974). The cloud microphysics, including the generation and possible re-evaporation of precipitation, are parameterised according to Sundqvist et al. (1989) and Sundqvist (1993).

Two GCM time slices of slightly longer than 10 years were used for both of the regional climate change experiments, denoted as RH (RCA/HadCM2) and RE (RCA/ECHAM4). One of the time slices acted as a control period and the other as a scenario period representing a future with higher greenhouse gas concentrations. No sulphate aerosol forcing was included in either RCA or the driving GCMs. The present analysis uses the last full 10 years of the four RCA runs.

The first few RCA simulated months are ignored to avoid spin-up.

The boundary data for RH are from partial reruns* of two long HadCM2 simulations; that is, a control run and a transient greenhouse run, in which gradually increasing CO₂ represents the change in greenhouse gas forcing from the pre-industrial era. The period used from the HadCM2 transient run is 2039–2049. The RE boundary forcing data are from a present-day (nominally 1980s) and a future (2070s) time slice from a transient ECHAM4/OPYC3 greenhouse run (as with RH, the first of these was a rerun). RH and RE therefore differ in terms of the periods, and this is also the case with the greenhouse gas-induced radiative forcing in the driving GCMs. The forcing in HadCM2, resulting from a 150% increase in CO₂, is about 20% larger than that in ECHAM4/OPYC3, in which increases are prescribed separately for CO₂, CH₄, N₂O and several CFCs (Fig. 0.3 of Machenhauer et al., 1998). Nevertheless, the global mean surface air warming between the two time slices is almost the same (2.6 K) in both of the two GCMs. In this sense, the RH and RE experiments do form a quantitatively comparable pair.

Regarding the changes in time mean temperature and precipitation, the conclusions of Räisänen et al. (2001) hold even for the present experiments. Even on the 44 km grid box scale, the differences between RCA and the driving GCM are typically smaller than the differences between the two GCM experiments. Thus, these aspects of the time mean climate change in RCA are strongly controlled by the driving GCMs. The lack of daily precipitation data for the GCMs prevents us from determining whether this is also true for the changes in extreme precipitation.

3. Control run precipitation

The 10-year average P_{mean} and P_{max} distributions in the two RCA control runs are mapped in

* Reruns were needed to obtain a data set detailed enough for driving RCMs. Because of the use of a different computer and a chaotic amplification of the associated (initially) bit-level differences, these reruns are not identical to the same decades in the original, longer HadCM2 simulations.

Fig. 1, together with the observed P_{mean} according to the CRU climatology for 1961–1990 (Hulme et al., 1995). The eight-point boundary zones are excluded from all figures and analysis in this paper.

Many of the geographical features of the observed P_{mean} are reproduced in the simulations. The land area spatial correlation with CRU is 0.79 for RH and 0.65 for RE, and the bias relative to the CRU land area mean +16% and +10%, respectively. As the CRU data have not been corrected for precipitation under-catch in the observations, the positive area mean biases are at least partly artificial. However, the modest area mean bias in RE results from a compensation between a clear negative bias in the southern-most part of the domain and substantial positive biases further north in central Europe and in Scandinavia. The biases also vary seasonally and are, in much of the area and both experiments, the most strongly positive in winter and in spring. These results are largely similar to those reported by Rummukainen et al. (2001) for an earlier 88 km version of the same model, although the P_{mean} in the present 44 km simulations is slightly larger in most of the area.

The 10-year mean P_{max} in the RCA control simulations is in most low-altitude areas around 30 mm day⁻¹. Larger values occur near the Alps and in western Norway, although the orographic contrasts are somewhat less pronounced than is the case with P_{mean} . Because of more limited data availability, P_{max} is more difficult to compare with observations than P_{mean} . Table 1 gives results for the 12 Swedish locations mapped in Fig. 2, comparing station observations for 1961–1990 with the closest RCA grid boxes. The agreement is reasonable. On the average, for this set of stations, P_{max} is underestimated by just 10% in RH and overestimated by just 9% in RE. According to a standard *t*-test (see Appendix A for the definition of this test and a discussion of its suitability for evaluating the significance of P_{max} differences), the differences between the simulated and observed P_{max} are statistically insignificant in most cases. As illustrated by the figures in the last row of the table, the inter-annual variability of P_{max} is also reasonably similar between the simulations and the station observations.

Given that the RCA grid boxes have an area of about 2000 km², it could be argued that the model should underestimate the P_{max} on the local scale

captured by the station observations. On the other hand, the real P_{max} is likely to be somewhat larger than that observed, because gauge measurements tend to undercatch precipitation. However, we speculate that this observational bias may be smaller for P_{max} than for P_{mean} , since the largest daily precipitation events in Sweden usually occur during the warmer part of the year when precipitation is liquid and the measurements are therefore less affected by aerodynamic effects. In any case, be it fortuitous or not, the agreement between the model and these Swedish station observations is better for P_{max} than for P_{mean} . The latter is overestimated, in particular in RE, seemingly due to an excessive number of light and moderate precipitation events.

4. Changes in average and extreme precipitation and some related quantities

4.1. Geographical distributions

The scenario minus control run precipitation changes ΔP_{mean} and ΔP_{max} are shown in Fig. 3, both in per cent of the control run means. P_{mean} increases in most of northern Europe and northern North Atlantic in both experiments, locally by up to 30%, but with somewhat different geographical patterns in RH and RE. In central Europe, slight decreases in P_{mean} dominate in RE, although the decrease is statistically significant at the 95% level in only a small part of the area. In RH, increases in P_{mean} extend further south than in RE. Near the southern edge of the map, some areas of significant decrease occur even in RH, but there are also strong local increases to the south of the Alps and in the south-eastern corner of the domain.

P_{max} increases in most of the domain in both RH and RE, including much of those areas where P_{mean} decreases. However, the geographical patterns of ΔP_{max} are extremely noisy, and the areas where ΔP_{max} is statistically significant are much more fragmented than is the case with ΔP_{mean} . This might suggest that the RCA experiments are too short to gain useful information on the P_{max} changes. However, as illustrated in Fig. 4, this is not true.

Fig. 4a shows the RE control and scenario run time series of P_{max} in a single grid box (identified in the lower right panel of Fig. 3) and Figs. 4b–c

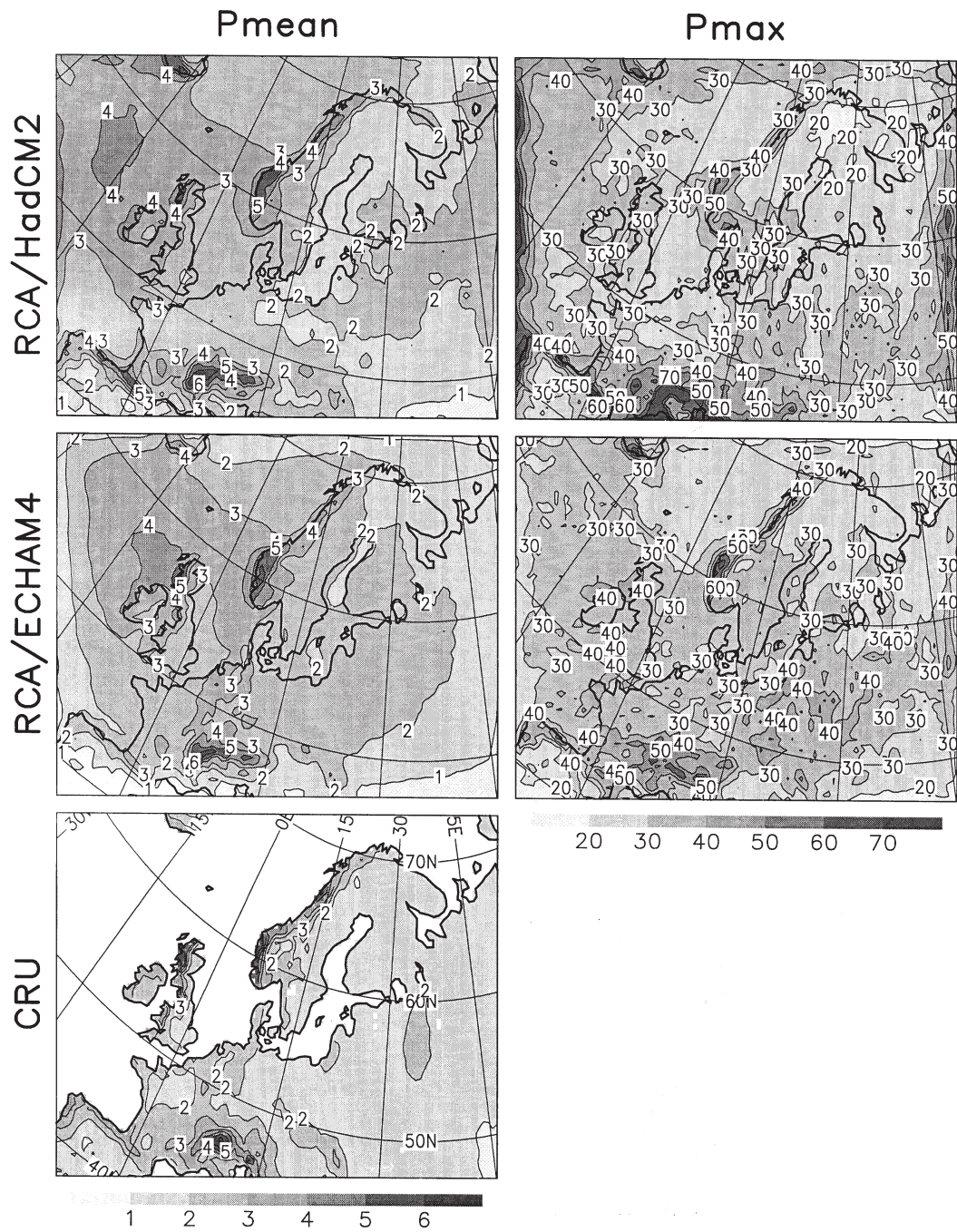


Fig. 1. Left: annual mean precipitation (mm day^{-1}) in the two RCA control runs and according to the CRU climatology for 1961–1990. Right: average yearly maximum one-day precipitation in the RCA control runs.

Table 1. Annual mean precipitation (P_{mean}) and mean yearly maximum one-day precipitation (P_{max}) at 12 Swedish sites according to station observations (1961–1990) and in the RH and RE control simulations. Simulated values that at the 95% significance level are different from those observed are marked in bold (positive differences) or by underlining (negative differences). The inter-annual standard deviation (SD) in the last row is the square root of the 12-station mean of the inter-annual variance

Station	P_{mean} (mm day ⁻¹)			P_{max} (mm day ⁻¹)		
	Obs	RH	RE	Obs	RH	RE
1 Växjö	1.79	2.27	2.81	30.1	36.6	36.6
2 Sävje	2.12	2.25	2.79	30.7	34.6	38.7
3 Stockholm	1.48	1.86	2.30	30.2	31.2	33.5
4 Karlstad	1.74	2.11	2.70	32.9	29.8	33.1
5 Uppsala	1.49	1.86	2.30	29.4	29.5	35.0
6 Falun	1.69	2.02	2.60	34.0	29.9	35.5
7 Härnösand	1.93	1.87	2.52	41.5	<u>32.2</u>	37.5
8 Östersund	1.33	1.90	2.56	29.4	<u>22.3</u>	40.5
9 Stensele	1.45	1.92	2.43	30.0	<u>23.4</u>	29.4
10 Haparanda	1.53	1.73	2.11	26.0	<u>20.3</u>	29.1
11 Jokkmokk	1.40	1.80	2.45	29.6	<u>22.2</u>	26.4
12 Katterjåkk	2.46	3.78	3.47	36.9	29.2	39.3
Average (Inter-annual SD)	1.70 (0.27)	2.11 (0.29)	2.59 (0.30)	31.7 (10.4)	<u>28.4</u> (8.5)	34.6 (12.1)

area means of P_{max} over the surrounding 7×7 and 17×17 grid boxes (310×310 km and 750×750 km, respectively). Finally, the area means over all land grid boxes in the map domain of Fig. 3 are given in Fig. 4d. In the single grid box, the control and the scenario run time series are both characterised by very strong inter-annual variability and they have, incidentally, almost identical 10-year means. However, the inter-annual variability decreases dramatically with an increasing averaging domain, which renders the difference between the two runs to be much more discernible. In the whole land area, the lowest yearly scenario run area mean of P_{max} exceeds the highest control run area mean, and the t -value of 8.0 (eq. (A1)) exceeds the threshold for 95% significance (2.101) by almost a factor of four. Thus, despite the strong small-scale noise, the experiments do provide statistically meaningful information on P_{max} changes on larger spatial scales. The noise associated with inter-annual variability and its implications for the interpretation of the RCA experiments will be discussed further in Section 5.

4.2. Area mean changes

Annual land area mean changes in P_{mean} and P_{max} along with some other precipitation para-

meters are given in Table 2. In addition to the whole land area, results are shown separately for the southern (S55 = land south of the latitude 55°N , which is indicated by the dashed line in Fig. 3) and northern (N55 = land north of 55°N) parts of the domain. As expected from Fig. 3, there is a contrast between the two sub-regions in ΔP_{mean} , between substantial increases in N55 and smaller, statistically insignificant changes (an increase in RH and a decrease in RE) in S55. By contrast, P_{max} increases significantly in both S55 and N55 in both experiments, in the latter area approximately as much as P_{mean} .

The largest one-day precipitation totals seldom result from temporally uniform precipitation during the whole 24-hour period. Therefore, we also calculated P_{max6} , the largest yearly six-hour precipitation (third row of Table 2). P_{max6} increases even more than P_{max} , in the whole land area mean by about 20% rather than 15%. The modified t -test described in the end of Appendix A indicates this difference to be highly statistically significant. Thus, the timescale of heavy precipitation appears to decrease. This is qualitatively consistent with a difference between the RH and RE control simulations. The simulated temperatures are generally higher in RE than in RH (on

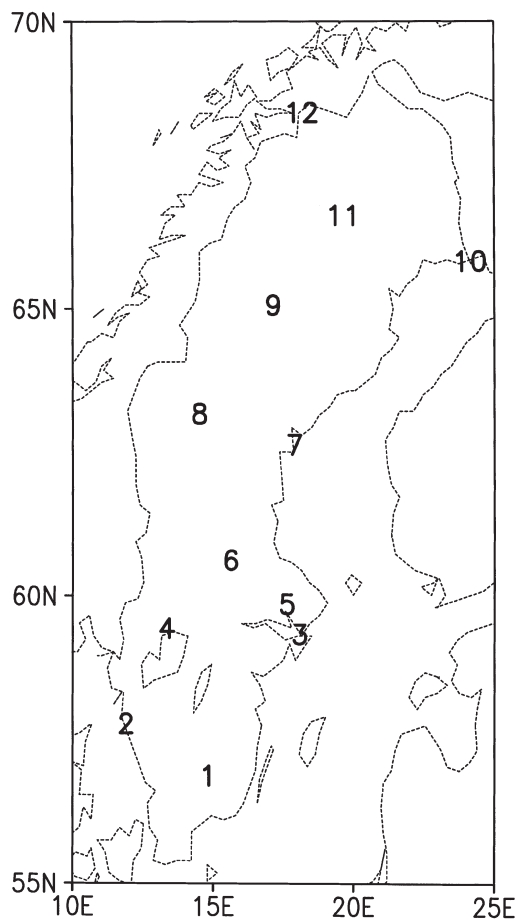


Fig. 2. The 12 Swedish stations used in Table 1.

the average, by 2°C in the lower troposphere), and so is the ratio between the control run area means of P_{max6} and P_{max} (compare rows 2 and 3 in Table 2). Nevertheless, the robustness of this result should be checked with other models.

Most of the extreme six-hour and one-day precipitation events in RCA are produced by stratiform condensation associated with ascent on the 44 km grid scale, rather than by deep convection. This feature may or may not be realistic. Comparison with observations is problematic both due to a lack of suitable digitised data sets and because the borderline between convective and stratiform precipitation is in reality ill-defined. Statistics for the simulated six-hour maxima of the stratiform and convective precipitation components are given on rows 4 and 5 in Table 2. The

scenario minus control run changes in the extremes of the dominating stratiform component are very similar to the changes in the extremes of total precipitation. The same is true even on the one-day timescale (not shown).

It is natural to think that a decrease in the timescale of heavy precipitation might be accompanied by a decrease in its horizontal scale. To study this possibility, the RCA simulated precipitation totals were replaced in each grid box by averages representing a typical GCM resolution (7×7 grid boxes $\approx 310 \times 310$ km). The average P_{max} and P_{max6} values for these series were then calculated in the usual manner. The results are, however, ambiguous (rows 6 and 7 in Table 2). The 310 km time series do yield slightly smaller per cent increases in P_{max} and especially P_{max6} than the grid-box-scale time series in RE, but there is little difference between the two scales in RH.

Different per cent changes in P_{max} and P_{mean} might, in principle, be explained by a change in wet-day frequency alone, with no change other than a constant relative shift in the probability distribution of wet-day precipitation. Alternatively, such differences might result from a redistribution of daily precipitation totals amongst a constant number of wet days (e.g. largest per cent increases in the upper end of the distribution). To study which of these alternatives is closer to the truth in the RCA experiments, the number of wet days with over 1 mm of precipitation (N_{wet}) and the average precipitation per wet day (precipitation intensity P_{wet}) were computed. Days with light precipitation of between 0.1 and 1 mm were excluded since, albeit their number in RCA is large (about 120 per year when averaged over the whole land area), they only contribute 6–7% to the total area mean precipitation.

N_{wet} (row 8 in Table 2) increases by about 5% in N55 but it decreases in S55, by 1.7% in RH and by as much as 12.5% in RE. Consequently, the changes in P_{wet} (row 9) are more similar between the two sub-regions, and in S55 between the two experiments, than are the changes in P_{mean} . P_{wet} increases in both sub-regions in both RH and RE, but not as much as P_{max} does (the difference $\Delta P_{\text{max}} - \Delta P_{\text{wet}}$ in the whole land area is statistically significant in both experiments). These results indicate that both the changes in wet-day frequency and the redistribution of precipitation

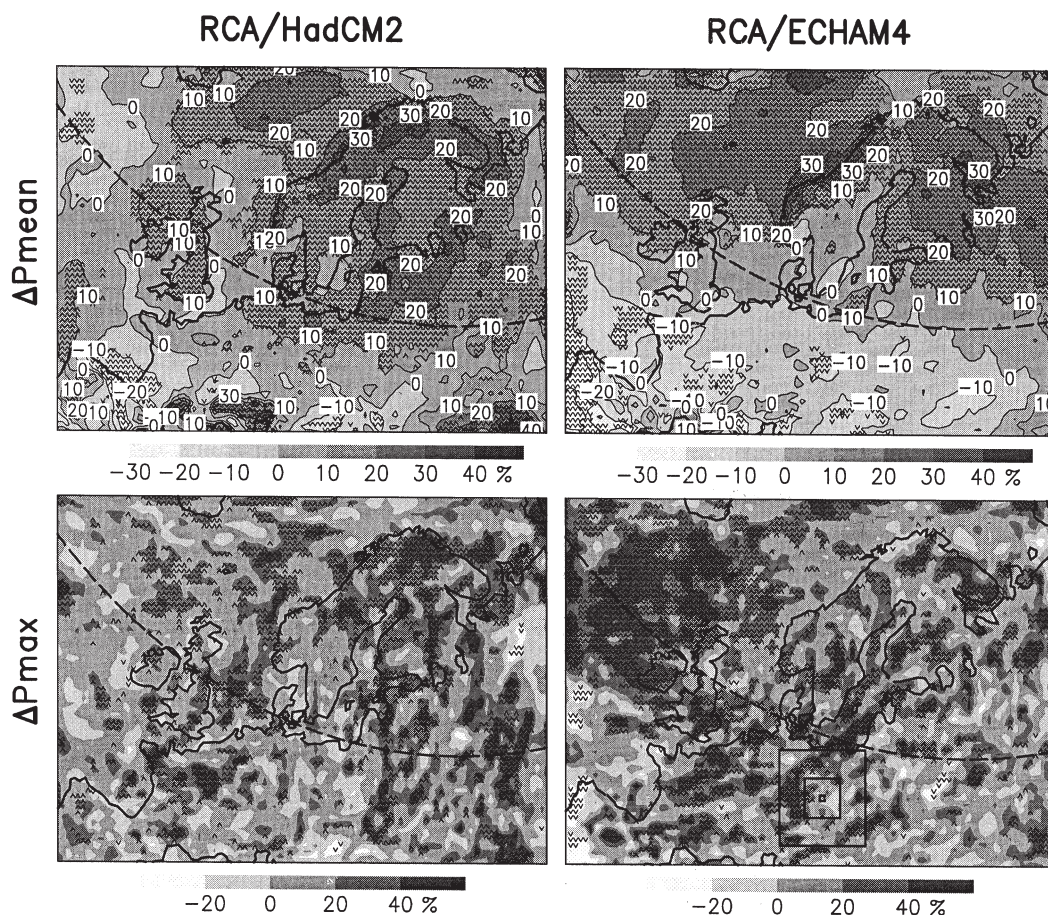


Fig. 3. Changes in annual mean precipitation (top; contours and shading at every 10%) and the average yearly maximum one-day precipitation (bottom; shading at every 20%) in the two RCA experiments. Changes that are statistically significant at the 95% level are indicated with small arrowheads. The thick dashed line shows the 55°N latitude. The three squares in the lower part of the bottom right panel are used in Fig. 4.

totals amongst the wet days contribute to the differences between ΔP_{max} and ΔP_{mean} .

Finally, for comparison with the changes in the average yearly precipitation extremes on rows 2 and 3 of Table 2, the changes in the absolute maximum one-day and six-hour precipitation for the whole ten-year period are given on rows 10 and 11. The increases in the absolute extremes are in a majority of cases slightly larger than those in the average annual extremes, but the difference is not systematic.

The seasonal distribution of the simulated P_{mean} , P_{wet} and P_{max} changes in the two sub-regions is shown in Fig. 5. Here, P_{max} is defined as the

10-year mean of the largest daily precipitation within a three-month season, which represents a somewhat less extreme event (frequency 1/90) than the annual P_{max} (1/360).

In N55, P_{mean} increases in all four seasons (DJF = December–February; MAM = March–May; JJA = June–August; SON = September–November), although the increase in JJA is much smaller in RE than in RH. In S55, P_{mean} only increases significantly in RH in MAM. The changes in the other seasons are within the 95% probability interval of internal variability, excluding a large decrease (23%) in RE in JJA that is explained by a 34% decrease in the number of

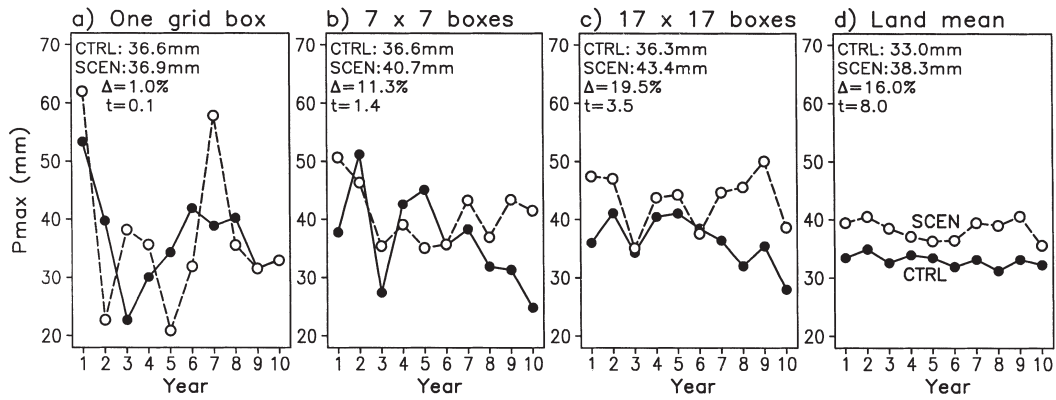


Fig. 4. Yearly values of $P_{\max}$ in the RE control run (solid lines) and scenario run (dashed lines). (a) shows the time series in the grid box indicated by the innermost square in the lower right panel of Fig. 3, (b) and (c) the area means over the surrounding 7×7 and 17×17 grid boxes (second and outermost squares, respectively), and (d) the area means over all land grid boxes in the map domain. CTRL, SCEN and Δ denote the control run 10-year mean, the scenario run 10-year mean and the relative change ($100\% \times (\text{SCEN}/\text{CTRL} - 1)$), respectively. t is the t -statistics from eq. (A1).

Table 2. Annual control run area means (CTRL; for the whole land area) and simulated changes (Δ ; for latitudes south (S55) and north (N55) of 55°N and for the whole land area) in some parameters

	CTRL, All		ΔS55 (%)		ΔN55 (%)		ΔAll (%)	
	RH	RE	RH	RE	RH	RE	RH	RE
1. P_{mean}	2.3	2.2 mm day ⁻¹	(5.4)	(-5.7)	17.1	15.8	10.5	(4.3)
2. P_{max}	33.5	33.0 mm day ⁻¹	12.1	15.8	18.6	16.2	14.6	16.0
3. $P_{\text{max}6}$	18.3	19.7 mm (6 h) ⁻¹	16.7	20.5	24.8	20.4	19.8	20.5
4. $P_{\text{max}6}$, stratiform	17.2	18.6 mm (6 h) ⁻¹	16.4	19.8	23.6	19.8	19.2	19.8
5. $P_{\text{max}6}$, convective	10.0	10.6 mm (6 h) ⁻¹	17.5	15.2	27.9	21.1	21.3	17.6
6. P_{max} , 310 km	22.2	22.1 mm day ⁻¹	13.3	14.1	18.0	14.9	15.2	14.5
7. $P_{\text{max}6}$, 310 km	9.2	10.3 mm (6 h) ⁻¹	18.3	14.9	23.5	18.3	20.5	16.4
8. N_{wet} (> 1 mm)	154	144 days	(-1.7)	-12.5	5.6	(4.7)	(1.8)	(-4.0)
9. P_{wet}	5.0	5.0 mm day ⁻¹	8.1	8.3	13.1	12.8	9.9	9.9
10. P_{max} , abs (10 yr)	56.3	56.0 mm day ⁻¹	11.0	19.7	20.6	12.7	14.6	16.8
11. $P_{\text{max}6}$, abs (10 yr)	32.8	35.6 mm (6 h) ⁻¹	17.1	24.5	26.8	18.2	20.6	22.0

All the changes in the last six columns are given in per cent of the control run area mean. Most of them are statistically significant at the 95% level according to the two-sided t -test (eq. (A1); applied on rows 1–9) or the pool permutation procedure of Preisendorfer and Barnett (1983) (rows 10–11); those that are not are given in parentheses.

wet days. By contrast, P_{wet} and P_{max} increase in all seasons in both sub-regions in both RH and RE. The increase in P_{max} exceeds that in P_{wet} with two exceptions in S55 (RE in JJA and RH in SON). $P_{\text{max}6}$ increases more than either of P_{wet} and P_{max} in all the cases considered (not shown).

The differences between RH and RE in the

seasonal and annual area means of P_{wet} and P_{max} change are, according to the modified t -test described in the end of Appendix A, all statistically insignificant (at the 95% level). The same is true for P_{mean} with the exception of JJA, when the change in mean precipitation in both N55 and S55 is significantly more positive in RH than in

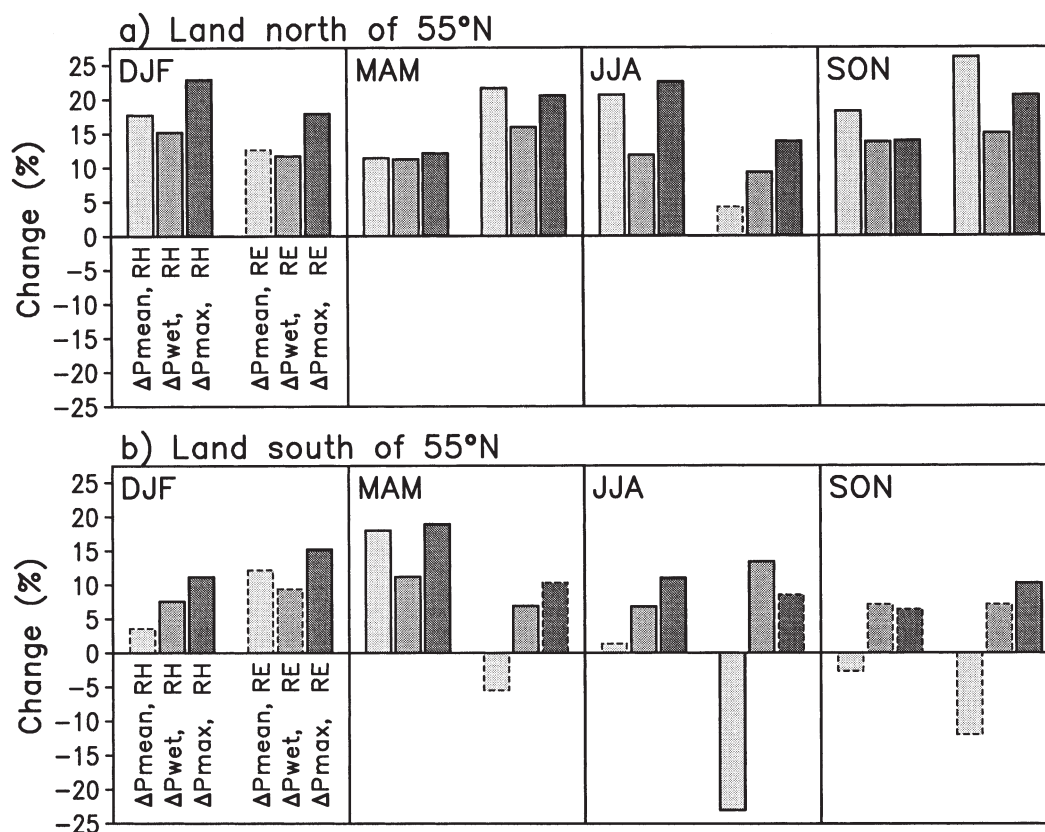


Fig. 5. Area mean seasonal changes in P_{mean} (light bars), P_{wet} (medium-dark bars) and P_{max} (dark bars) in the RH (first three bars in each box) and RE (last three bars) experiments. Solid (dashed) bar outline indicates that the changes are (are not) significant at the 95% level. (a) Land north of 55°N; (b) land south of 55°N.

RE. This difference is at least partly related to contrasting changes in the summertime atmospheric circulation. The scenario minus control run differences in JJA sea level pressure and lower tropospheric geopotential heights in RH feature a low pressure cell over Scandinavia, whereas the pattern in RE is dominated by a high centred over the North Sea (not shown). As a result, the changes in atmospheric moisture convergence are more positive in RH (corresponding to about 11% of the control run area mean precipitation in N55 and -6% in S55) than in RE (-2% in N55 and -19% in S55). The decrease in JJA precipitation in RE in S55 appears to be exacerbated by a decrease in evaporation (corresponding to 4% of the control run precipitation, in contrast with a 7% increase in RH) associated with reduced soil moisture.

4.3. Factors affecting the extremes of stratiform precipitation

Simulated greenhouse gas-induced increases in heavy precipitation have frequently been linked to the rapid increase in atmospheric moisture-holding capacity with increasing temperature (e.g. Gordon et al., 1992; Frei et al., 1998). Precipitation is, however, proportional to the rate at which moisture is removed from the atmosphere, not to the moisture content as such. Some of the factors that are relevant for understanding the RCA-simulated changes in the extremes of (in this model, dominant) stratiform precipitation are discussed below. Related annual land area mean statistics for a lower (850 hPa) and a mid-tropospheric pressure level (500 hPa) are given in Table 3.

Table 3. Control run land area means and simulated area mean changes in some parameters at 850 and 500 hPa

	CTRL, 850 hPa		CTRL, 500 hPa		Change, 850 hPa		Change, 500 hPa	
	RH	RE	RH	RE	RH	RE	RH	RE
1. T	272.3	274.3	251.2	254.5 K	3.2 K	3.7 K	3.8 K	4.2 K
2. RH	0.759	0.725	0.601	0.578 [1]	-0.014	-0.017	-0.008	-0.020
3. q	4.4	5.0	0.8	1.0 g kg ⁻¹	21.9%	25.9%	42.9%	44.5%
4. $(-\omega)_{\max}$	1.5	1.5	2.3	2.3 Pa s ⁻¹	2.1%	(1.6%)	11.1%	7.5%
5. $(-\omega q)_{\max}$	10.5	12.1	3.4	4.3×10^{-3} Pa s ⁻¹	24.4%	27.2%	56.7%	59.3%
6. $C_{\max}$	2.3	2.4	2.7	3.2×10^{-7} s ⁻¹	10.5%	8.3%	38.7%	35.2%

T , temperature; RH , relative humidity, q , specific humidity; $(-\omega)_{\max}$, average yearly maximum pressure co-ordinate rising motion; $(-\omega q)_{\max}$, maximum upward moisture flux; $C_{\max}$, maximum pseudo-adiabatic condensation rate (see text). The changes in temperature and relative humidity are given in absolute units and the changes in the other parameters in per cent of the control run area mean. Changes that are not statistically significant at the 95% level are given in parentheses.

The land area annual mean warming in the two experiments is 3.2–3.7 K at 850 hPa and 3.8–4.2 K at 500 hPa (row 1 of Table 3). Consequently, the average specific humidity q increases by 22–26% at 850 hPa and by 43–45% at 500 hPa, despite a slight decrease in relative humidity (rows 2 and 3). The per cent increase in q is larger in the middle than in the lower troposphere mainly because the saturation pressure is in relative terms more sensitive to temperature in cold conditions (see eq. (2) below). The average vertically integrated moisture content increases by 25% in RH and by 28% in RE.

Precipitation requires condensation induced by rising motion. A large enough decrease in the intensity of the strongest rising motions could therefore lead to weaker precipitation extremes in a warmer climate. However, this does not happen in the RCA simulations. The changes in the ten-year area means of the yearly maximum pressure co-ordinate rising motion $(-\omega)_{\max}$, diagnosed from instantaneous ω -fields stored at six-hour intervals, are shown on row 4 of Table 3. At 500 hPa, in particular, the average $(-\omega)_{\max}$ is substantially larger in the scenario than in the control runs (by 11% in RH and 8% in RE), perhaps due to the stronger latent heat release allowed by the larger moisture content. Consistent with the increase in $(-\omega)_{\max}$, the yearly extremes of upward moisture flux $(-\omega q)_{\max}$ increase even more than the specific humidity at both 850 and 500 hPa (row 5 of Table 3).

From the increase in the extremes of rising motion, one might expect $P_{\max}$ and $P_{\max 6}$ to increase more than the atmospheric moisture content, and not less, as is actually the case. The apparent discrepancy may be partly a question of timescale: the ω -fields used in deriving $(-\omega)_{\max}$ are instantaneous snapshots of model output, rather than 6- or 24-hour averages. However, there is another factor at play. In pseudo-adiabatic ascent, which is a good approximation when latent heat release is much stronger than other sources of diabatic heating, the condensation rate increases less steeply with atmospheric temperature than the moisture content does. First, the latent heat release associated with condensation counteracts the cooling induced by rising motion, as indicated by the thermodynamic equation

$$c_p \frac{dT}{dt} = \frac{RT}{p} \omega - L \frac{dq_s}{dt} \quad (1)$$

(for the symbols in eqs. (1)–(4), see Table 4). Therefore, for the same rising motion, the larger condensation rate $-dq_s/dt$ makes the cooling of saturated air slower at higher temperatures. Second, the Clausius–Clapeyron relationship

$$\frac{1}{e_s} \frac{de_s}{dT} = \frac{L}{R_v T^2} \quad (2)$$

indicates that the water vapour saturation pressure e_s , which is related to the saturation specific

Table 4. Symbols used in eqs. (1)–(4)

Symbol	Explanation
c_p	Specific heat capacity of air at constant pressure (for dry air, $1004 \text{ J kg}^{-1} \text{ K}^{-1}$)
e_s	Saturation pressure of water vapour
L	Latent heat of vaporisation ($2.5 \times 10^6 \text{ J kg}^{-1}$) or sublimation ($2.834 \times 10^6 \text{ J kg}^{-1}$): the latter value is used at $T < 273.15 \text{ K}$
q_s	Specific humidity of saturated air
p	Pressure
R	Gas constant of a mixture of dry air and water vapour (for dry air, $287 \text{ J kg}^{-1} \text{ K}^{-1}$)
R_v	Gas constant of water vapour ($461 \text{ J kg}^{-1} \text{ K}^{-1}$)
t	Time
T	Temperature
ω	Vertical motion in pressure co-ordinates (dp/dt)

humidity q_s via

$$q_s = \frac{R}{R_v} \frac{e_s}{p} \quad (3)$$

is in relative terms most sensitive to temperature in cold conditions. Thus, for the same amount of pseudo-adiabatic cooling, warmer air will lose a smaller fraction of its water vapour by condensation.

Equations (1)–(3) can be combined to derive the rate at which condensation occurs in a pseudo-adiabatically rising saturated air parcel. When one neglects in eq. (3) the fact that the gas constant R for a mixture of dry air and water vapour is a weak function of specific humidity (Rogers and Yau, 1989, p. 18), the result becomes

$$C \equiv -\frac{dq_s}{dt} \approx -\omega \frac{q_s}{p} \frac{\frac{RL}{R_v c_p T} - 1}{\frac{L^2 q_s}{R_v c_p T^2} + 1} \quad (4)$$

This quantity was evaluated from the six-hourly RCA output, and its average yearly maxima ($C_{\max}$) were calculated for each grid box. In this calculation, only cases with a relative humidity of over 90% were considered (however, this has little impact on the results because strong ascent is generally accompanied with high humidity). The values in the last row of Table 3 were obtained by assuming condensation to ice ($L =$

$2.834 \times 10^6 \text{ J kg}^{-1}$ instead of $2.5 \times 10^6 \text{ J kg}^{-1}$) at temperatures below 273.15 K and by neglecting the slight humidity dependence of c_p and R (Rogers and Yau, 1989, p. 18). However, the calculation was repeated by using $L = 2.5 \times 10^6 \text{ J kg}^{-1}$ at all temperatures and by including the mentioned humidity dependencies, and the results were found to be reasonably insensitive to the details of the methodology. The calculated maximum condensation rate increases in the land area mean by about 10% at 850 hPa and by 35–40% at 500 hPa. These increases are smaller than the increases in specific humidity and, in particular, the maximum upward moisture flux at the same levels.

By integrating C vertically, one can estimate the rate of pseudo-adiabatic condensation in the whole atmospheric column. This calculation includes some numerical uncertainty associated with the coarse vertical resolution (150–200 hPa) of the RCA output, but it suggests that the yearly maxima of vertically integrated condensation rate in the control runs have an average magnitude of 5–6 mm per hour and that the maxima in the scenario runs are about 25% larger. Both the control run values and the relative change are larger than the corresponding results for $P_{\max 6}$ in Section 4.2, but recalling that eq. (4) yields instantaneous rather than temporally averaged condensation rates, the differences are not implausible. Nonetheless, it is also important to note that eq. (4) represents a gross simplification of the parameterisation of stratiform precipitation in RCA. For example, condensed water vapour in the model does not fall down immediately but is rather first converted to cloud water that may be advected to neighbouring grid boxes.

4.4. Wet-day frequency and atmospheric circulation

The results in Section 4.2 indicate that the larger contrast between $\Delta P_{\max}$ and ΔP_{mean} in the southern than in the northern part of the RCA domain can be mainly explained by different changes in wet-day frequency (N_{wet}). One factor that likely affects the N_{wet} changes is changes in atmospheric circulation. The RH and RE experiments both show greater annually averaged increases in the 850 hPa height Z850 in the southern than in the northern part of the domain (Fig. 6). This pattern of change suggests a northward shift in cyclone activity (which is supported by changes in band-pass

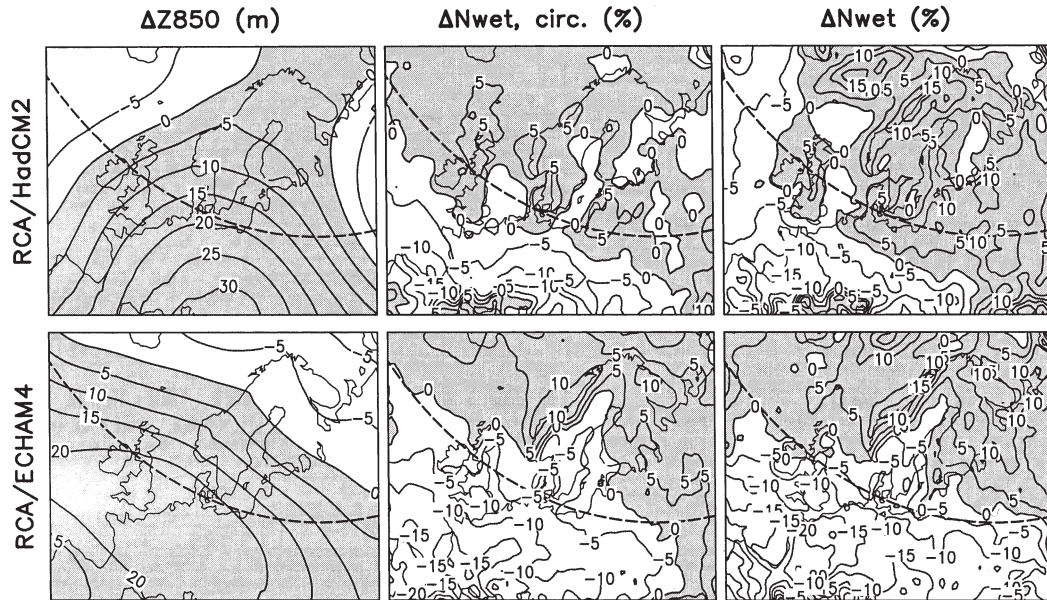


Fig. 6. Changes in the annual mean of Z850 (left, metres), the changes in the number of wet days inferred with the regression model (5) (middle, % of control run mean), and the actual simulated changes in the number of wet days (right). Positive values are shaded.

filtered height variability) and increased westerly flow from the Atlantic Ocean to northern Europe. Further south, $\Delta Z850$ indicates a shift towards more anti-cyclonic conditions, in particular in RE where $\Delta Z850$ is a maximum over western and central Europe. The annual Z850 changes in both RH and RE are reasonably large compared with internal variability (the threshold for 95% significance is about 10 m), but the differences between the two experiments are much harder to distinguish from noise. In both RH and RE, the increased north–south gradient in Z850 is particularly pronounced in autumn.

To estimate how such circulation changes might contribute to the changes in the number of wet days, a regression model was applied:

$$\Delta N_{\text{wet,circ}} = A_1 \Delta Z850'' + A_2 \frac{\partial}{\partial \lambda} \Delta Z850 + A_3 \frac{\partial}{\partial \varphi} \Delta Z850 \quad (5)$$

where Δ indicates a difference between the scenario and control run means and λ and φ are the model longitude and latitude, respectively. $Z850''$ is the difference between the local Z850 and its area

mean over the whole model domain (see below). The frequency of precipitation days is expected to be related to both how cyclonic or anti-cyclonic the lower tropospheric flow is (precipitation tends to be more probable in cyclonic conditions) and the wind vector, which affects moisture and temperature advection and orographic vertical motions. $\Delta Z850''$ is (the gradients of $\Delta Z850$ are) used as an indicator of the former (latter) aspect of the circulation change.

The coefficients A_1 – A_3 were derived separately for each grid box and each calendar month, using interannual variability in both the control and the scenario runs. First, monthly anomalies of N_{wet} and the three predictors were calculated with respect to the corresponding control and scenario run 10-year monthly means. Then, a least-square linear regression was made using the 20 sets of control and scenario run anomalies simultaneously. In systematic cross-verification (that is, when each of the 20 anomalies was predicted, in turn, by a regression based on the remaining 19 anomalies), this model explained 43% (46%) of the inter-annual variance of local monthly N_{wet} anomalies in RH (RE). The corresponding

fractions of explained variance for the best two-predictor (Z'' and $\partial Z''/\partial \phi$) and one-predictor (Z'') models were 37% (40%) and 25% (27%), respectively.

The changes in the annual wet-day frequency obtained by applying eq. (5) to the monthly 10-year mean scenario minus control Z850 differences are shown in the mid-column of Fig. 6. The large-scale pattern of the actual changes (right column), with increases in the northern and decreases in the southern part of the domain, is qualitatively well reproduced, and the same also applies to some of the finer-scale details. The area mean N_{wet} changes from the regression in N55 and S55 are 1.7% and -3.3% for RH, and 3.1% and -8.4% for RE, respectively. Comparison with the actual values (Table 2, row 8) suggests that a substantial part of the contrasts between the two sub-regions, and between RH and RE in S55, are related to circulation changes, albeit with the caveat that the apparent similarity is no proof of a direct cause–effect relationship. However, the predicted increase in N55 and the predicted decrease in RE in S55 are somewhat smaller than those simulated. The latter difference is largest in the summer, which may be related to substantially reduced soil moisture in RE in S55.

The use of the 850 hPa level in this exercise is somewhat arbitrary. However, other levels between 500 and 1000 hPa give largely similar results when the area mean height change is neglected in the regression. When the area mean is retained, the inferred ΔN_{wet} grows increasingly more negative when higher levels are used. This is because the overall rise of pressure surfaces due to the warmer temperatures is erroneously “interpreted” by the regression model as an indication of more anti-cyclonic conditions.

5. The signal-to-noise issue

In the previous section, the statistical significance of the simulated P_{mean} and P_{max} changes was estimated by using the t -test. However, regardless of whether the changes are significant or not, they are quantitatively affected by the noise in the short (10-year) simulations. In other words, the inferred scenario run minus control run climate changes are unlikely to be identical with the noise-free

climate change signal specific to the model system used. How large is this “error” likely to be?

The noise-free climate change signal is defined here as the climate change that would be obtained by averaging over a large ensemble of experiments with the same greenhouse gas forcing, but with different (RCM and driving GCM) initial conditions (this signal may naturally be affected by model errors). The statistically expected magnitude of the noise-related error is characterised, in principle, by the variance between the individual ensemble members. In practice, we estimated this variance ($V10$) from the variability within the 10-year simulations, as described in Appendix B. A basic assumption in this method, which we believe to be quite well justified for precipitation, is that individual years are statistically independent from each other.

In Table 5 the standard error (square root of the land area mean of $V10$) associated with internal variability is given for the annual P_{max} and P_{mean} changes on four slightly arbitrarily selected horizontal scales. In addition to the local, grid-box-scale changes, area mean changes on the 310 km and 750 km scales and over the whole land area are considered. The 310 km and 750 km scale changes are defined separately for each grid box, using means over the surrounding 7×7 or 17×17 grid boxes, before averaging the associated $V10$ over the whole land area. As above, all changes and their standard errors are measured in relative terms (% of control run mean).

The results for RH and RE are similar. Grid-box-scale values of ΔP_{max} have a standard error of about 20%, while the standard error for local ΔP_{mean} is only about 8%. However, the inter-

Table 5. *Standard error (%) due to internal variability for simulated changes in P_{mean} and P_{max} on different horizontal scales (310 km = mean over 7×7 grid boxes; 750 km = mean over 17×17 grid boxes)*

	RH		RE	
	P_{max}	P_{mean}	P_{max}	P_{mean}
Grid box	19.2	8.0	20.0	8.4
310 km	9.5	6.7	9.6	7.3
750 km	5.9	5.5	5.7	6.2
Land mean	2.5	1.7	2.1	3.5

annual variations of $P_{\max}$ have a smaller horizontal scale than those of P_{mean} , and horizontal averaging therefore reduces the standard error of $\Delta P_{\max}$ more rapidly than the error of ΔP_{mean} . On the two largest scales (750 km and land area mean), the error estimates for the two parameters are, perhaps surprisingly, quite similar to each other.

Using the $V10$ estimates and the actual simulated climate changes, it is of interest to complement the t -test results discussed in Section 4 with a statistic that we call the *change-to-noise ratio* (CN). This is calculated as

$$CN = \frac{\overline{(\Delta P)^2}}{V10} \quad (6)$$

where the wavy lines denote area means over the whole land area and ΔP refers to either of ΔP_{mean} or $\Delta P_{\max}$. CN can also be evaluated (in an analogous way) for the $\Delta P_{\max} - \Delta P_{\text{mean}}$ difference and for the differences in ΔP_{mean} and $\Delta P_{\max}$ between RH and RE.

At the limit of large samples (i.e., infinite number of independent grid boxes), the internal variability and the real climate change signal can be assumed to be uncorrelated with each other, and are therefore additive in terms of the squared amplitude. In this case, $CN = 2$ indicates that the signal and the noise have equal magnitude. This remains a useful first guideline of interpretation even when dealing with the more limited samples studied here. However, it should also be stressed that the interpretation of CN becomes increasingly uncertain with decreasing sample size. Thus, although CN is evaluated in Table 6 for horizontally averaged (310 km scale to land area mean) as well as for local climate changes, the results on the largest scales are, at best, suggestive. The main indications from this table are the following:

(1) Grid-box-scale changes in $P_{\max}$ have a relatively low CN ratio (more than a half of the squared amplitude is attributed to internal varia-

bility). Local P_{mean} changes are somewhat less severely contaminated by internal variability.

(2) The CN ratios increase with increasing horizontal scale, excluding the low ratio (1.5) for the area mean ΔP_{mean} in RE that reflects a near cancellation between opposing changes in the northern and southern parts of the domain. Even when this feature is disregarded, the difference in the scale dependence of noise makes the increase in CN with increasing scale steeper for $\Delta P_{\max}$ than for ΔP_{mean} .

(3) The $\Delta P_{\max} - \Delta P_{\text{mean}}$ differences have a higher CN ratio in RE than in RH.

(4) The previous result is difficult to interpret, because a majority of the RH – RE differences in both $\Delta P_{\max}$ and ΔP_{mean} seem to arise from internal variability at least up to the 750 km scale.

The last point also suggests that, if longer RCA experiments had been made using boundary data from the same two GCMs, the differences between RH and RE might have been substantially smaller. Of course, the only rigorous way to verify this suggestion would be to actually conduct such longer experiments.

Finally, we consider an issue that is of importance in climate change impact research. The results in Table 5 indicate that, disregarding sources of uncertainty other than internal variability, model results give much better estimates of large-scale area means of $\Delta P_{\max}$ than of the local changes. However, in many impact studies, it is the local climate change that matters. Should this be estimated directly from the simulated grid box values, despite the strong noise, or should the grid box values be averaged over a larger area? The latter strategy reduces the noise, but, on the other hand, the local climate change signal may differ from the larger-scale signal. Putting this in quantitative terms, the statistically expected squared error E^2 for estimating the local noise-free climate

Table 6. The change-to-noise ratio (see text) for some parameters on different scales

	RH			RE			RH – RE	
	$\Delta P_{\max}$	ΔP_{mean}	$\Delta P_{\max} - \Delta P_{\text{mean}}$	$\Delta P_{\max}$	ΔP_{mean}	$\Delta P_{\max} - \Delta P_{\text{mean}}$	$\Delta P_{\max}$	ΔP_{mean}
Grid box	1.8	3.9	1.1	1.8	3.3	1.9	1.1	1.7
310 km	4.1	4.5	1.4	4.0	3.9	4.3	1.3	1.7
750 km	8.4	5.8	1.6	9.1	4.7	7.5	1.3	1.5
Land mean	34.8	38.4	2.3	58.8	1.5	13.0	0.2	2.6

change signal from a simulated large-scale mean climate change is

$$E^2 = V10_{LS} + (S_{LOC} - S_{LS})^2 \quad (7)$$

where $V10_{LS}$ is the variance associated with the internal variability of the large-scale mean climate change ("noise error") and $(S_{LOC} - S_{LS})^2$ is the squared difference between the local climate change signal and the larger-scale mean signal ("signal error").

An obvious problem with eq. (7) is that the signals S_{LOC} and S_{LS} are both unknown. Their squared difference can only be estimated as a residual, by subtracting from the squared difference between the simulated local (ΔP_{LOC}) and larger-scale (ΔP_{LS}) climate changes the squared difference *on average* expected from internal variability, that is, the variance $V10_{LOC-LS}$ characterising the noise in $\Delta P_{LOC} - \Delta P_{LS}$

$$(S_{LOC} - S_{LS})^2 \approx (\Delta P_{LOC} - \Delta P_{LS})^2 - V10_{LOC-LS} \quad (8)$$

The words "on average" in the previous sentence are important. In any single grid box, the squared difference between ΔP_{LOC} and ΔP_{LS} may be much larger or smaller than its statistically expected value. In the latter case, the inferred $(S_{LOC} - S_{LS})^2$ may be substantially negative. Even when averaged over the whole land area, there is, in several of the cases studied, a strong cancellation between the two right-hand-side terms in eq. (8). For example, when estimating the local ΔP_{max} in RE from ΔP_{max} on the 750 km scale, the area mean of $(\Delta P_{LOC} - \Delta P_{LS})^2$ is 382%² and that of $V10_{LOC-LS}$ 352%². The values for RH are 321%² and 322%², respectively, which gives a physically unrealistic difference of -1%². Obviously, $(S_{LOC} - S_{LS})^2$ cannot be estimated very accurately. However, the strong cancellation itself is important, since it implies that a large majority of the small-scale variations in ΔP_{max} are indeed likely to be noise.

The calculated total root-mean-square (r.m.s.) errors (square root of the area mean of E^2) for estimating the local ΔP_{max} signal from the simulated ΔP_{max} on different scales are given in the first data row of Table 7. Also given are, in parentheses, the r.m.s. values of the signal error (8) alone; as discussed above, these are quite uncertain. In any case, the results for the total r.m.s. error in RH and RE are qualitatively similar. The signal difference is far too small to outweigh the

advantage of reduced noise when the local ΔP_{max} is replaced with larger-scale means. For RH, the r.m.s. error is estimated to be smallest when using the 750 km scale means (5.9%), for RE when using the mean for the whole land area (7.4%). Thus, in both cases, substantially better estimates of the local ΔP_{max} signal appear to be obtainable by a strong horizontal averaging of the results.

Should horizontal averaging also be used when estimating the change in the mean rather than the maximum precipitation? The results in this case are less clear-cut (second row of Table 7). Nevertheless, a smoothing up to the 750 km scale does not appear to worsen the ΔP_{mean} estimates in either RH or RE.

Experiments longer than those discussed here would be less strongly affected by internal variability, which would make the benefits of horizontal averaging smaller. As an example, the last row in Table 7 shows the hypothetical error estimates for inferring the ΔP_{max} signal from 40-year rather than 10-year simulations. The noise variance is assumed to scale inversely with the averaging period, whereas the signal error is independent of the period. Thus, the r.m.s. error for using the local value of ΔP_{max} as such is halved, whereas in the cases in which signal error is also involved, the relative decrease in r.m.s. error is smaller. Nevertheless, some averaging of the raw model results (at least up to the 310 km scale) would still appear to be useful.

6. Summary

Two regional 44 km resolution climate change experiments for northern and central Europe have been analysed focussing mainly on the changes in annual mean precipitation (P_{mean}) and the yearly maximum one-day precipitation (P_{max}). Each experiment consists of a 10-year control run and a 10-year scenario run representing a possible future with higher greenhouse gas concentrations and, in both the two driving GCMs, a 2.6 K higher global mean temperature. The main findings are listed below.

(1) The control run P_{mean} distributions show a reasonable pattern similarity with the observed distribution, but the simulated P_{mean} exceeds the observed values in much of the model area. At

Table 7. Statistically estimated root-mean-square error (%) when approximating the local noise-free climate change signal in $P_{\max}$ or P_{mean} with the simulated change in the same parameter on different horizontal scales (the contribution of the signal error is given in parentheses)

	RH				RE			
	Grid box	310 km	750 km	Land mean	Grid box	310 km	750 km	Land mean
$\Delta P_{\max}$	19.2 (0.0)	9.5 (0.0)	5.9 (0.0)	6.3 (5.8)	20.0 (0.0)	10.2 (3.5)	7.9 (5.5)	7.4 (7.1)
ΔP_{mean}	8.0 (0.0)	7.8 (4.0)	8.0 (5.8)	7.6 (7.4)	8.4 (0.0)	7.7 (2.4)	7.0 (3.2)	13.2 (12.7)
$\Delta P_{\max}$, 40 yr of data	9.6 (0.0)	4.7 (0.0)	2.9 (0.0)	5.9 (5.8)	10.0 (0.0)	5.9 (3.5)	6.2 (5.5)	7.2 (7.1)

the 12 Swedish stations studied, the simulated $P_{\max}$ has quite a realistic magnitude.

(2) In the scenario runs, P_{mean} increases in northern Europe but decreases further south over the continent, especially in one of the two experiments. $P_{\max}$ increases on the average by 15% and the increase even extends to most of the areas where P_{mean} decreases.

(3) The decrease in P_{mean} in the southern part of the domain can be explained by a decrease in the number of wet days with at least 1 mm of precipitation. Further north, the wet-day frequency generally increases in the experiments. This dipole pattern is at least partly associated with changes in atmospheric circulation.

(4) The average precipitation for all wet days increases in both central and northern Europe, but generally somewhat less than $P_{\max}$.

(5) The timescale of heavy precipitation appears to decrease. The average increase in the yearly maximum six-hour precipitation, about 20% in both experiments, exceeds that in the one-day $P_{\max}$. Calculations of the pseudo-adiabatic condensation rate hint that the increase in maximum instantaneous precipitation rates might be even larger.

(6) The grid-box-scale changes in $P_{\max}$ are heavily affected by internal variability in the short simulations, much more so than the changes in P_{mean} . However, the error associated with this noise can be reduced substantially by a horizontal averaging of the results. The disadvantage that such averaging also smoothens out part of the real climate change signal is, in the case of the $P_{\max}$ changes, much smaller than the advantage of reduced noise.

(7) A large part of the differences in P_{mean} and $P_{\max}$ changes between the two experiments may be explained by the brevity of the simulations.

Some of these results should be checked with other models (in particular, the decrease in the timescale of heavy precipitation) or by conducting longer simulations (the importance of internal variability). However, our basic finding of stronger precipitation extremes in a warmer climate is by no means new. Thus, to the extent that this can be addressed by comparing different model simulations, a general intensification of heavy precipitation events may be regarded as being a very probable consequence of an enhanced greenhouse effect.

7. Acknowledgements

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8. Appendix A

Testing statistical significance

To test whether there is a statistically significant difference in mean between two samples of yearly data, such as the control run and observations or the scenario run and the control run, the t -statistic is used. If the two samples consist of n_X and n_Y values and have means M_X and M_Y and (“ $n - 1$ ” form) variances V_X and V_Y , then

$$t = \frac{M_Y - M_X}{V_{XY}^{1/2}} \quad (\text{A1})$$

where

$$V_{XY} = \left(\frac{1}{n_X} + \frac{1}{n_Y} \right) \frac{(n_X - 1)V_X + (n_Y - 1)V_Y}{n_X + n_Y - 2}. \quad (\text{A2})$$

In the comparison between the RCA control and scenario runs $n_X = n_Y = 10$, so that

$$V_{XY} = \frac{V_X + V_Y}{10} \quad (\text{A3})$$

and the statistics have $n_X + n_Y - 2 = 18$ degrees of freedom. The critical absolute t -value for two-sided 95% significance in this case is 2.101.

The test (A1) assumes that the data are not serially correlated, that they are normally distributed, and that the two samples come from populations with equal variance. Serial correlation is difficult to judge from short time series but we do not expect it to be a serious problem in the case of yearly $P_{\max}$ and P_{mean} values. Deviations from normality might appear to be a bigger issue, at least for $P_{\max}$, but the t -test is relatively insensitive to these. We also applied, to many of the cases studied, a significance test based on the pool permutation procedure of Preisendorfer and Barnett (1983), which does not require normally distributed data. The resulting significance levels were almost identical with those obtained from eq. (A1). Possible differences in variance can be approximately accounted for as described by von Storch and Zwiers (1999, p. 113). Such a procedure was also tested and was found to yield only modest changes to the significance estimates based on eq. (A1), in particular when comparing the RCA scenario and control runs with equal sample size.

The test (A1) is used to judge whether the scenario minus control run climate change in a given parameter in a given experiment differs

significantly from zero. Another important but more delicate question is whether or not two relative (%) climate changes are significantly different from each other (e.g. is $\Delta P_{\max}$ in RH significantly different from ΔP_{mean} in RH, or from $\Delta P_{\max}$ in RE). This is tested as described by Räisänen et al. (2001). Denoting the yearly control (scenario) run values in the two data sets compared as X_1 and X_2 (Y_1 and Y_2), the test (A1) is applied to the 10-year means and variances of

$$X_{\text{Diff}} = X_1 - AX_2 \quad (\text{A4})$$

and

$$Y_{\text{Diff}} = Y_1 - AY_2 \quad (\text{A5})$$

where the coefficient A is calculated from the 10-year means of X_1 , X_2 , Y_1 and Y_2 as

$$A = \frac{M_{X1} + M_{Y1}}{M_{X2} + M_{Y2}} \quad (\text{A6})$$

This scaling ensures that $t = 0$ when the relative (%) scenario minus control climate change is the same in both cases.

9. Appendix B

Error associated with internal variability

To estimate the magnitude of error that internal variability is likely to cause to the relative P_{mean} and $P_{\max}$ changes in the 10-year experiments, the experiments were first divided into two 5-year parts. Assuming that the individual years are statistically independent from each other, the ordering of the years does not matter and this division can be done in $(10!)/(5!)^2 = 252$ different ways. In each case, the relative scenario minus control climate change was calculated separately for these two 5-year samples. Denoting the two 5-year estimates of climate change as $F1$ and $F2$, the estimate for the variance of 5-year climate changes becomes

$$V5 = \frac{1}{2} \overline{(F1 - F2)^2} \quad (\text{B1})$$

where the over-line indicates averaging over all choices of the two 5-year periods. The variance of 10-year climate changes is estimated as

$$V10 = \frac{5}{10} V5, \quad (\text{B2})$$

assuming that the variance is inversely proportional to the averaging period. This assumption is, in the absence of inter-annual auto-correlation, exactly true when the scenario minus control differences are measured in absolute units. To study how well it holds for the relative (%) differences used here, (B2) was replaced with the more general form

$$Vn = \frac{n}{10} Vn, \quad (\text{B3})$$

where Vn denotes the variance of n -year ($n \leq 5$) climate changes estimated with the same principle as $V5$. Taking the grid box scale changes in $P_{\max}$ in RE as a characteristic example, $n = 3$ yielded a 2% higher estimate of the area mean of $V10$ than $n = 5$. For $n = 2$ and $n = 1$, the difference increased to 4% and 14%, respectively. Extrapolating to the other direction, the $V10$ estimates from (B2) may

also be slightly too large but the error appears small.

It might be tempting to estimate $V10$ simply as

$$V10 \approx V_{XY} \left(\frac{100\%}{M_X} \right)^2 \quad (\text{B4})$$

where V_{XY} is the variance used in the t -test (A3) and M_X is the 10-year control run mean. This would, however, give biased results. As discussed by Räisänen et al. (2001), the sensitivity of a relative (%) scenario minus control run climate change to random variations in the control run mean depends on the relative change itself. For example, when $P_{\max}$ is 20% larger in the scenario than in the control run, a further 1% perturbation in the control run mean causes a -1.2% rather than -1% perturbation in the relative change.

The method described above can be generalised in an obvious way to estimating the variance in the difference between two climate changes (e.g. $\Delta P_{\max} - \Delta P_{\text{mean}}$).

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